

On dynamic topological logics

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joint work with

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The Story

S. Artemov, J. Davoren and A. Nerode.

Topological semantics for hybrid systems.

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J. Davoren. *Modal logics for continuous dynamics.*

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Ph. Kremer and G. Mints. *Dynamic topological logic.*

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Bimodal logics for reasoning about continuous dynamics.

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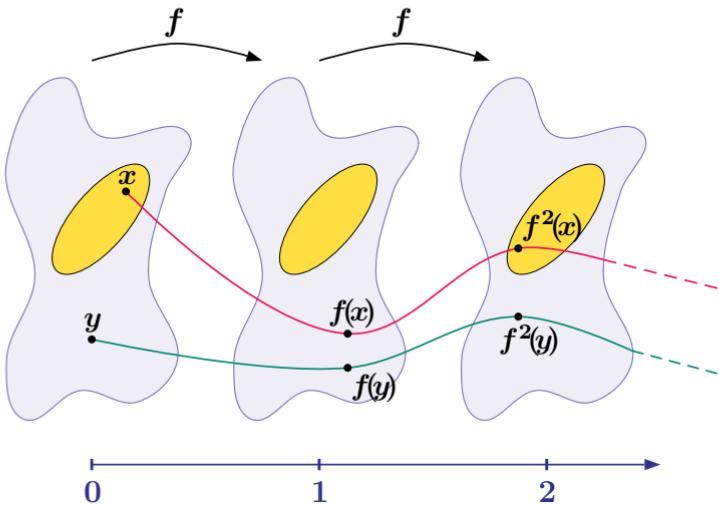
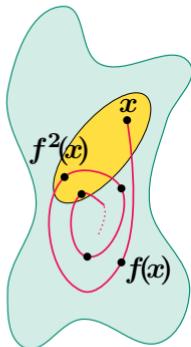
B. Konev, R. Kontchakov, F. Wolter and M. Zakharyashev.

On dynamic topological and metric logics.

Proceedings of AiML 2004, pp. 182–196, Manchester, U.K., September 2004

Dynamical systems

'space' + f



$$\text{Orb}_f(x) = \{ f(x), f^2(x), \dots \} \quad - \text{the orbit of } x$$

Temporal logic \times logic of topology

to describe and reason about the (asymptotic) behaviour of orbits

Dynamic topological structures

Dynamic topological structure $\mathfrak{F} = \langle \mathfrak{T}, f \rangle$

$\mathfrak{T} = \langle T, \mathbb{I} \rangle$ a **topological space**

- T is the universe of \mathfrak{T}
- \mathbb{I} is the interior operator on \mathfrak{T}
- \mathbb{C} is the closure operator on \mathfrak{T}
 $(\mathbb{C}X = -\mathbb{I} - X)$

- arbitrary topologies
- Aleksandrov: **arbitrary** (not only finite) intersections of open sets are open
 - every Kripke frame $\mathfrak{G} = \langle U, R \rangle$, where R is a **quasi-order**, induces the Aleksandrov topological space $\langle U, \mathbb{I}_{\mathfrak{G}} \rangle$:
 $\mathbb{I}_{\mathfrak{G}}X = \{x \in U \mid \forall y (xRy \rightarrow y \in X)\}$
 - conversely, every Aleksandrov space is induced by a quasi-order
- Euclidean spaces $\mathbb{R}^n, n \geq 1$
- ...

$f: T \rightarrow T$ a **continuous function** $(X \text{ open } \Rightarrow f^{-1}(X) \text{ open})$

- continuous
- homeomorphisms $(\text{continuous bijections with continuous inverses})$

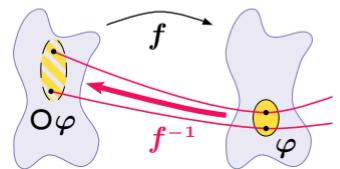
Dynamic topological logic \mathcal{DTL}

Formulas:

\mathfrak{V} a **valuation** in $\langle \langle T, \mathbb{I} \rangle, f \rangle$

- propositional variables p, q, \dots subsets of T
- the Booleans \neg, \wedge and \vee \neg, \cap and \cup
- topological ('modal') operators \mathbf{I} and \mathbf{C} \mathbb{I} and \mathbb{C}
- temporal operators \mathbf{O}, \Box_F and \Diamond_F $\mathfrak{V}(\mathbf{O}\varphi) = f^{-1}(\mathfrak{V}(\varphi))$

$$\mathfrak{V}(\Box_F \varphi) = \bigcap_{n=1}^{\infty} f^{-n}(\mathfrak{V}(\varphi)) = \{x \in T \mid \mathbf{Orb}_f(x) \subseteq \mathfrak{V}(\varphi)\}$$



$$\mathfrak{V}(\Diamond_F \varphi) = \bigcup_{n=1}^{\infty} f^{-n}(\mathfrak{V}(\varphi)) = \{x \in T \mid \mathbf{Orb}_f(x) \cap \mathfrak{V}(\varphi) \neq \emptyset\}$$

Example: every ψ satisfies φ infinitely often $\psi \rightarrow \Box_F \Diamond_F \varphi$

Known results: no ‘infinite’ operations

\mathcal{DTL}_O — subset of \mathcal{DTL} containing no ‘infinite’ operators (\Box_F and \Diamond_F)

Artemov, Davoren & Nerode (1997): The two dynamic topo-logics

$$\text{Log}_O\{\langle \mathfrak{F}, f \rangle\} \quad \text{and} \quad \text{Log}_O\{\langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space}\}$$

coincide, have the **fmp**, are finitely **axiomatisable**, and so decidable

NB. $\text{Log}_O\{\langle \mathfrak{F}, f \rangle\} \subsetneq \text{Log}_O\{\langle \mathbb{R}, f \rangle\}$ (Slavnov 2003, Kremer & Mints 2003)

Kremer, Mints & Rybakov (1997): The three dynamic topo-logics

$$\text{Log}_O\{\langle \mathfrak{F}, f \rangle \mid f \text{ a homeomorphism}\},$$

$$\text{Log}_O\{\langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space, } f \text{ a homeomorphism}\},$$

$$\text{Log}_O\{\langle \mathbb{R}^n, f \rangle \mid f \text{ a homeomorphism}\}, \ n \geq 1,$$

coincide, have the **fmp**, are finitely **axiomatisable**, and so decidable

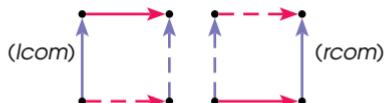
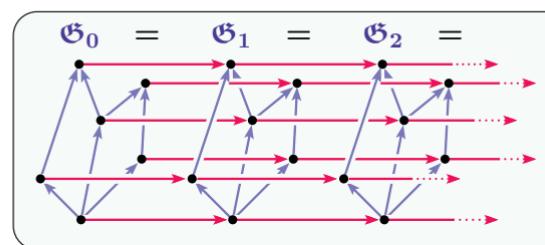
Homeomorphisms vs. continuous mappings

$\mathfrak{T} = \langle U, \mathbb{I} \rangle$ is the Aleksandrov space induced by a quasi-order $\mathfrak{G} = \langle U, R \rangle$

f is a **homeomorphism**

$$xRy \Leftrightarrow f(x)Rf(y)$$

a DTM can be **unwound** into
a product model



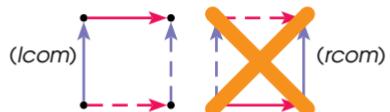
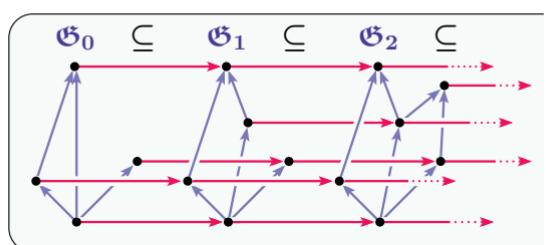
$$\mathbf{S4} \oplus \mathbf{DAlt} \oplus (\mathbf{O} \mid p \leftrightarrow \mathbf{I} \mathbf{Op})$$

f is **continuous**

$$xRy \Rightarrow f(x)Rf(y)$$

a DTM can be **unwound** into

an e-product model



$$\mathbf{S4} \oplus \mathbf{DAlt} \oplus (\mathbf{O} \mid p \rightarrow \mathbf{I} \mathbf{Op})$$

DTLs with homeomorphisms

Theorem 1 (AiML 2004). No logic from the list below is recursively enumerable:

- $\text{Log } \{\langle \mathfrak{F}, f \rangle \mid f \text{ a homeomorphism}\},$
- $\text{Log } \{\langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space, } f \text{ a homeomorphism}\},$
- $\text{Log } \{\langle \mathbb{R}^n, f \rangle \mid f \text{ a homeomorphism}\}, \ n \geq 1.$

Proof. By reduction of the undecidable but r.e. Post's Correspondence Problem
to the satisfiability problem

(more on the next slide)

NB. All these logics are different.

Encoding PCP

PCP: given a set of pairs $\{(u_1, v_1), \dots, (u_k, v_k)\}$ of nonempty finite words, decide whether there exists an $N \geq 1$ and a sequence i_1, \dots, i_N such that

$$u_{i_1} \cdot u_{i_2} \cdot \dots \cdot u_{i_N} = v_{i_1} \cdot v_{i_2} \cdot \dots \cdot v_{i_N}$$

Post (1946):

The PCP is undecidable and the set of PCP instances without solutions is not R.E.

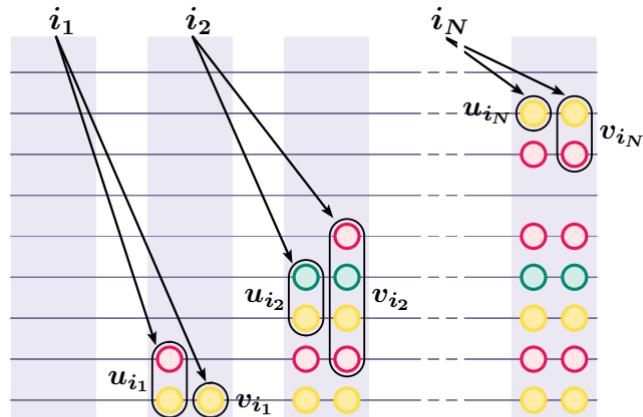
- Aleksandrov space $\langle U, \mathbb{I} \rangle$
(induced by $\langle U, R \rangle$)

'local' formulas

$$\Box_F^+ I(\psi_1 \rightarrow O\psi_2)$$

plus

$$\Diamond_F \bigwedge_{a \in A} I(L_a \leftrightarrow R_a)$$



- arbitrary topological spaces and \mathbb{R}^n :
the formula requires only a **finite** number of iterations
and thus the completeness results for $\text{Log}_O\{\dots\}$ can be used

DTLs with continuous mappings

Theorem 2. No logic from the list below is decidable:

- $\text{Log } \{\langle \mathfrak{F}, f \rangle\}$,
- $\text{Log } \{\langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space}\}$,
- $\text{Log } \{\langle \mathbb{R}^n, f \rangle\}, n \geq 1$.

Proof. By reduction of

the undecidable ω -reachability problem for lossy channels
to the satisfiability problem

(more on the next slide)

NB. All these logics are different.

Encoding lossy channels backwards

Single channel system

$$S = \langle Q, \Sigma, \Delta \rangle$$

Q — a set of *control states*

Σ — an alphabet of *messages*

$\Delta \subseteq Q \times \{?, !\} \times \Sigma \times Q$ — a set of *transitions*

send

$$\langle q, w \rangle \xrightarrow{\langle q, !, a, q' \rangle} \ell \langle q', w' \rangle$$

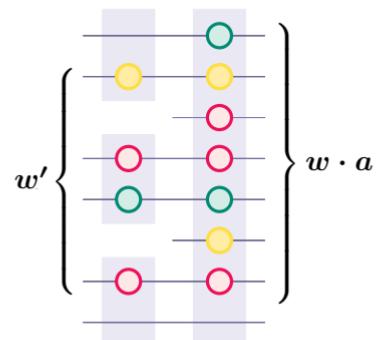
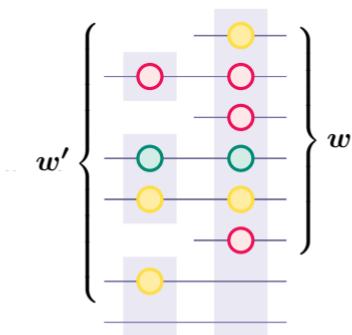
iff $w' \sqsubseteq a \cdot w$

receive

$$\langle q, w \cdot a \rangle \xrightarrow{\langle q, ?, a, q' \rangle} \ell \langle q', w' \rangle$$

iff $w' \sqsubseteq w$

backward encoding: loss of messages = introduction of new points



Encoding lossy channels: ω -reachability (1)

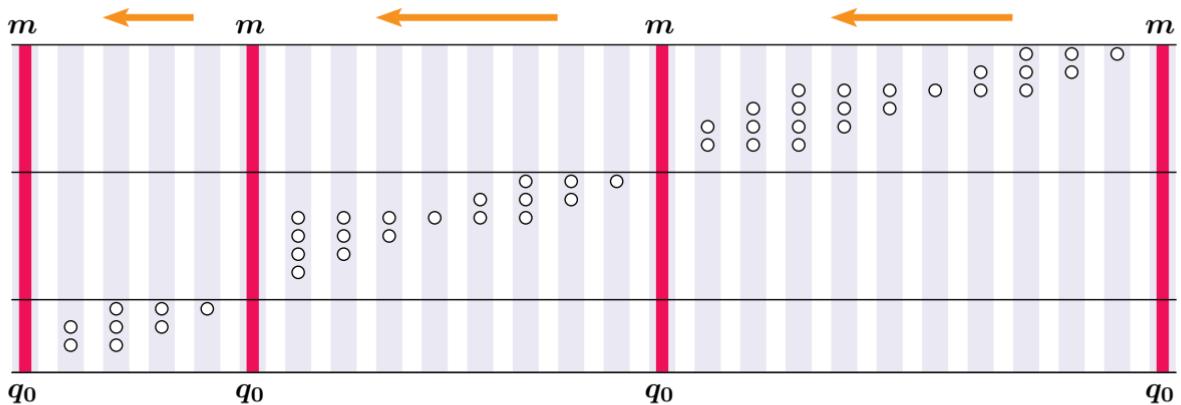
ω -reachability:

given a single channel lossy system S and two states q_0 and q_{rec} ,
decide whether, **for every $n > 0$** , there is a computation

$$\langle q_0, \epsilon \rangle \xrightarrow{\delta_1}_\ell \langle q_{i_1}, w_1 \rangle \xrightarrow{\delta_2}_\ell \langle q_{i_2}, w_2 \rangle \xrightarrow{\delta_3}_\ell \dots$$

reaching q_{rec} **at least n times**

Schnoebelen (2004): ω -reachability is undecidable



The ω -reachability problem can be encoded

using only 'local' formulas

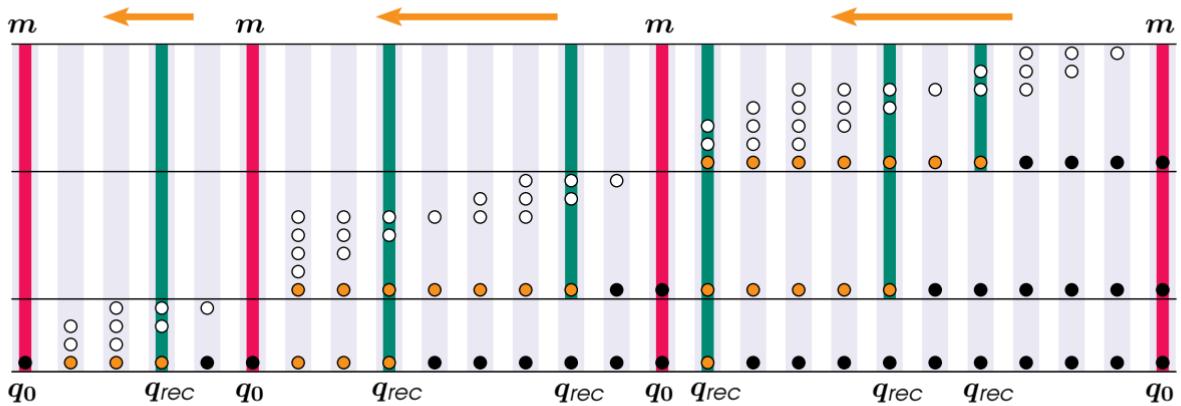
$$\Box_F^+ I(\psi_1 \rightarrow O\psi_2)$$

plus

$$\Box_F \Diamond_F m$$

plus...

Encoding lossy channels: ω -reachability (2)



$light \wedge \square_F^+(light \rightarrow \text{O } light)$

$\square_F^+(m \rightarrow \text{O I}(light \rightarrow on))$

$\square_F^+(\mathbf{C}(light \wedge on \wedge \text{O} \neg on) \rightarrow q_{rec})$

$\square_F^+(m \rightarrow \mathbf{I}(light \rightarrow \neg on))$

$\square_F(m \rightarrow \mathbf{I}(light \rightarrow \text{O S } light))$

$\square_F^+ \mathbf{I}((light \wedge on \wedge \text{O} \neg on) \rightarrow \neg \mathbf{S}(light \wedge on \wedge \text{O} \neg on))$

Finite iterations

- arbitrary finite flows of time
- finite change assumption (the system eventually stabilises)

Theorem 3 (APAL 2006). The two topo-logics

$$\text{Log}_{\text{fin}} \{ \langle \mathfrak{F}, f \rangle \} \quad \text{and} \quad \text{Log}_{\text{fin}} \{ \langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space} \}$$

coincide and are **decidable**, but **not in primitive recursive time**

Proof. By Kruskal's tree theorem and

reduction of the reachability problem for lossy channels

(decidable but not in primitive recursive time)

However:

Theorem 4 (AiML 2004). The two topo-logics

$$\text{Log}_{\text{fin}} \{ \langle \mathfrak{F}, f \rangle \mid f \text{ a homeomorphism} \} \quad \text{and}$$

$$\text{Log}_{\text{fin}} \{ \langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space, } f \text{ a homeomorphism} \}$$

coincide but are **not recursively enumerable**

Open problems

- Axiomatisation of DTL over Euclidean spaces (without $\square_F, \diamondsuit_F$)
- Are full DTLs with continuous mappings r.e.?
- If so, are they finitely axiomatisable? Axiomatisations?
- ...

Publications (all available on the web)

- 1) B. Konev, R. Kontchakov, F. Wolter and M. Zakharyaschev.
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- 2) D. Gabelaia, A. Kurucz, F. Wolter and M. Zakharyaschev.
Non-primitive recursive decidability of products of modal logics with expanding domains
Annals of Pure and Applied Logic, 142:245–268, 2006

- 3) B. Konev, R. Kontchakov, F. Wolter and M. Zakharyaschev.
On dynamic topological and metric logics
Studia Logica, 84:127–158, 2006

- 4) B. Konev, F. Wolter and M. Zakharyaschev.
Temporal logics over transitive states
LNCS 3632, (R. Nieuwenhuis ed.), pp.182–203, Springer, 2005 (Proc. of CADE-05)

- 5) B. Konev, R. Kontchakov, F. Wolter and M. Zakharyaschev.
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Proc. of AiML 2004, September 2004, Manchester, U.K.