

On dynamic topological and metric logics

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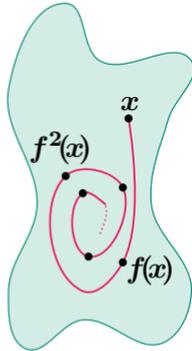
<http://www.dcs.kcl.ac.uk/staff/romanvk>

joint work with

Boris Konev, Frank Wolter and Michael Zakharyashev

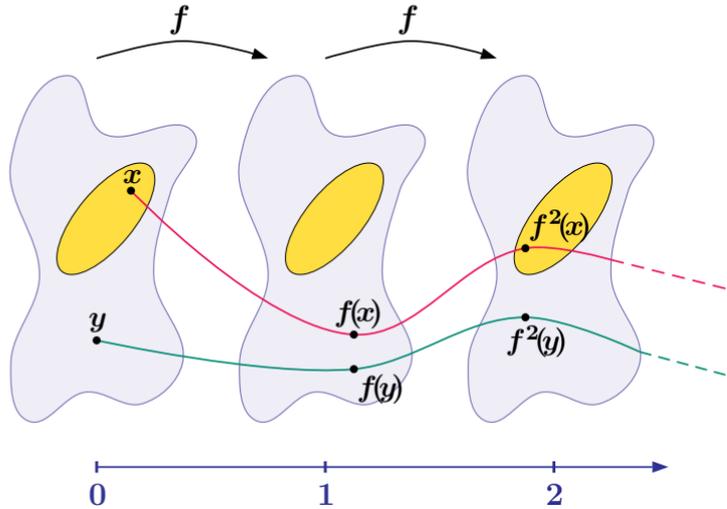
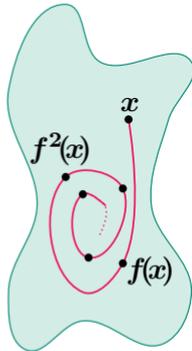
Dynamic systems

'space' + f



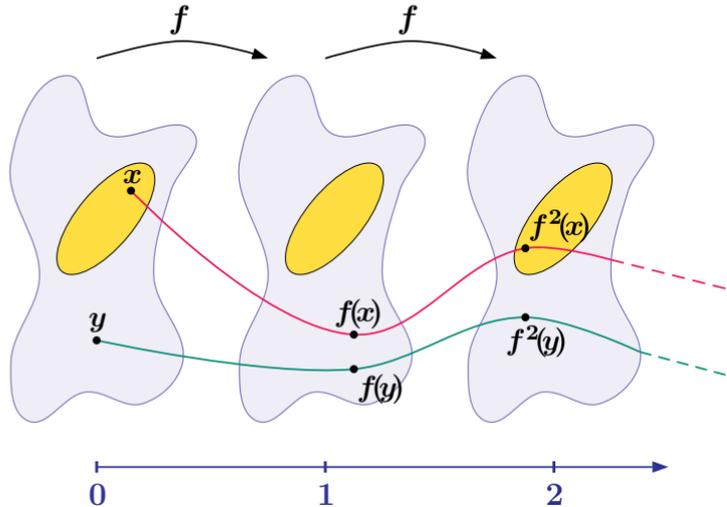
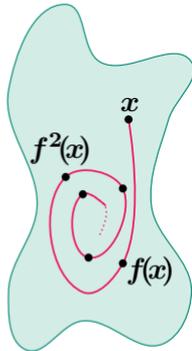
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Temporal logic to describe and reason about behaviour of dynamic systems:

- variables p are interpreted by sets of points, i.e., point x is in p : $x \in p$
- x always stays in p : $x \in \Box_F p$
- x occurs in p infinitely often: $x \in \Box_F \Diamond_F p$
- ...

Dynamic topological logic

Dynamic topological structure $\mathfrak{F} = \langle \mathfrak{T}, f \rangle$

$\mathfrak{T} = \langle T, \mathbb{I} \rangle$ a topological space

T is the universe of \mathfrak{T}

\mathbb{I} is the interior operator on \mathfrak{T}

\mathbb{C} is the closure operator on \mathfrak{T}

$$(\mathbb{C}X = -\mathbb{I} - X)$$

$f: T \rightarrow T$ a total continuous function

(X open $\Rightarrow f^{-1}(X)$ open)

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Dynamic topo-logic \mathcal{DTL}

- propositional variables p, q, \dots
- the Booleans \neg, \wedge and \vee
- modal (topological) operators \mathbb{I} and \mathbb{C}
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subsets of T

\neg, \cap and \cup

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$$\mathfrak{V}(\circ\varphi) = f^{-1}(\mathfrak{V}(\varphi))$$

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Classes of dynamic topological structures

Topological spaces $\mathfrak{T} = \langle T, \mathbb{I} \rangle$

- arbitrary topologies
- Aleksandrov: **arbitrary** (not only finite) intersections of open sets are open
 - every Kripke frame $\mathfrak{G} = \langle U, R \rangle$, where R is a **quasi-order**, induces the Aleksandrov topological space $\langle U, \mathbb{I}_{\mathfrak{G}} \rangle$:
$$\mathbb{I}_{\mathfrak{G}}X = \{x \in U \mid \forall y (xRy \rightarrow y \in X)\}$$
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Functions $f: T \rightarrow T$

- continuous
- homeomorphisms: continuous bijections with continuous inverses
- ...

Known results

\mathcal{DTL}_\circ — subset of \mathcal{DTL} containing **no 'infinite'** operators (\Box_F and \Diamond_F)

Artemov, Davoren & Nerode (1997): The two dynamic topo-logics

$\text{Log}_\circ\{\langle \mathfrak{F}, f \rangle\}$ and $\text{Log}_\circ\{\langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space}\}$

coincide, have the **fmp**, are finitely **axiomatisable**, and so decidable.

NB. $\text{Log}_\circ\{\langle \mathfrak{F}, f \rangle\} \subsetneq \text{Log}_\circ\{\langle \mathbb{R}, f \rangle\}$ (Slavnov 2003, Kremer & Mints 2003)

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Open problem: axiomatisations and algorithmic properties of the **full \mathcal{DTL}** ?

Homeomorphisms: bad news

Theorem 1. No logic from the list below is **recursively enumerable**:

- $\text{Log } \{\langle \mathfrak{X}, f \rangle \mid f \text{ a homeomorphism}\},$
- $\text{Log } \{\langle \mathfrak{X}, f \rangle \mid \mathfrak{X} \text{ an Aleksandrov space, } f \text{ a homeomorphism}\},$
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Proof. By reduction of the undecidable but r.e. Post's Correspondence Problem to the satisfiability problem.

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NB. All these logics are **different**.

Continuous maps: some good news

Finite iterations:

- arbitrary finite flows of time
- finite change assumption (the system eventually stabilises)

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Theorem 2. The two topo-logics

$\text{Log}^* \{ \langle \mathfrak{F}, f \rangle \}$ and $\text{Log}^* \{ \langle \mathfrak{F}, f \rangle \mid \mathfrak{F} \text{ an Aleksandrov space} \}$

coincide and are **decidable**, but **not in primitive recursive** time.

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However:

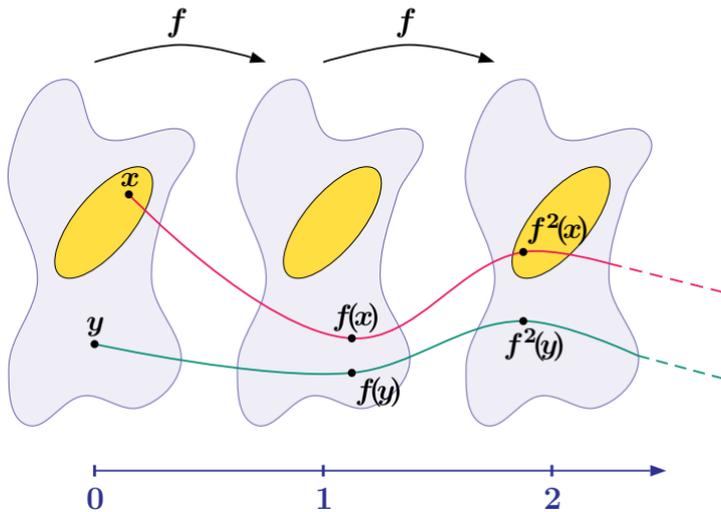
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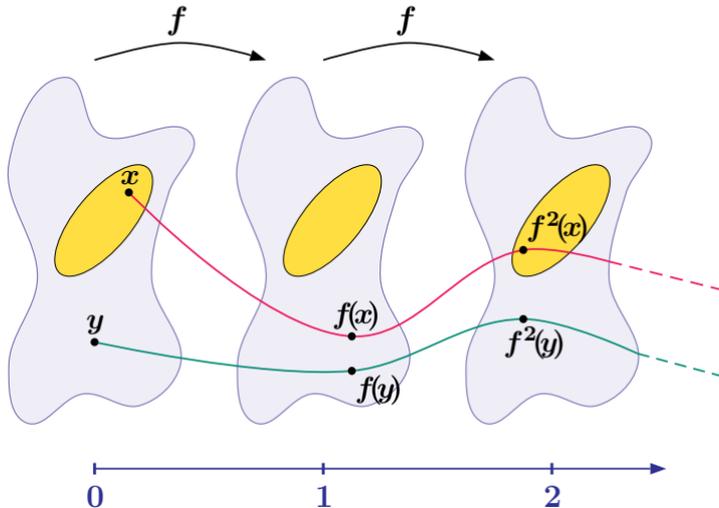
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coincide but are **not recursively enumerable**.

Dynamics in metric spaces



Dynamics in metric spaces



A **metric space** $\mathfrak{D} = \langle W, d \rangle$, where $d: W \times W \rightarrow \mathbb{R}^+$ is a metric, induces the **topological space** $\mathfrak{T}_d = \langle W, \mathbb{I}_d \rangle$:

$$\mathbb{I}_d X = \{x \in W \mid \exists \delta > 0 \forall y \in W (d(x, y) < \delta \rightarrow y \in X)\}$$

Logics of metric spaces

$\mathfrak{D} = \langle W, d \rangle$ a metric space

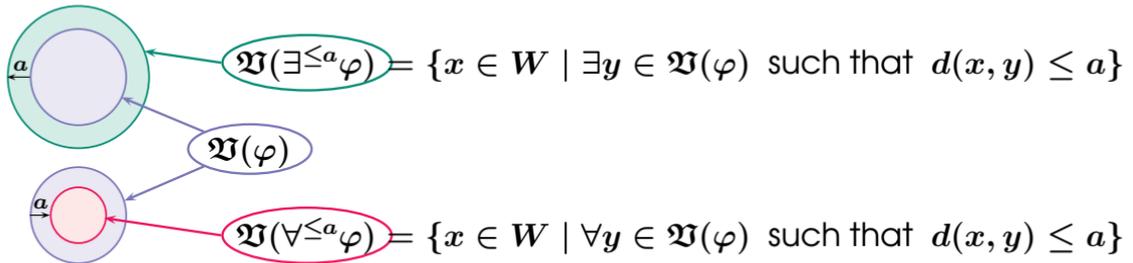
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- the Booleans \neg, \wedge and \vee
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- metric operators $\exists^{\leq a}$ and $\forall^{\leq a}$, for $a \in \mathbb{Q}^+$

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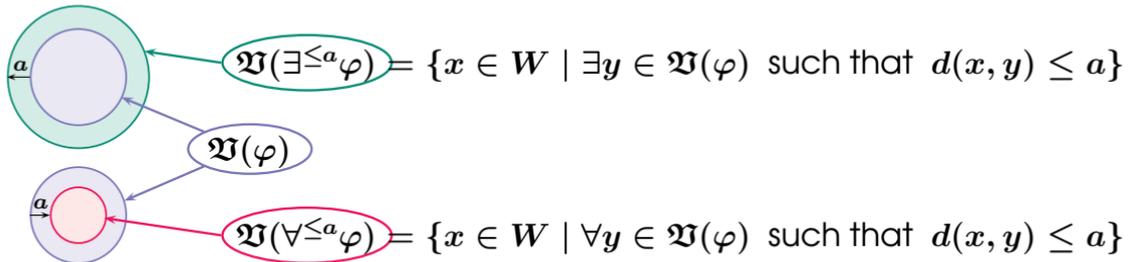


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Wolter & Zakharyashev (2004):

The set of valid \mathcal{MT} -formulas is **axiomatisable**.

The satisfiability of \mathcal{MT} -formulas is **EXPTIME-complete**.

Dynamic metric logic

Dynamic metric structure $\mathfrak{F} = \langle \mathfrak{D}, f \rangle$

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$f: W \rightarrow W$ a metric automorphism (bijection, $d(f(x), f(y)) = d(x, y)$)

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Dynamic metric logic $\mathcal{DM}\mathcal{L}$

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Theorem 4. The set of valid $\mathcal{DM}\mathcal{L}$ -formulas is **decidable**.

However, the decision problem is **not elementary**.

Proof. Quasimodels, reduction to monadic second-order logic and yardsticks.

Open problems and future research

The field still remains a big research challenge. . .

- Axiomatisation of decidable logics/fragments
- Various topological and metric spaces: Euclidean, compact, etc.
- functions: Lipschitz continuous, contracting maps, etc.
- Model checking
- . . .